

# Image Object Extraction using Resistive-Fuse and Oscillator Networks and a Pulse-Modulation Circuit for their LSI Implementation

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## 1. Introduction

In order to recognize a natural scene image, which usually includes several objects, we should segment the image into several recognition target objects and extract them one by one. In this paper, we propose a new object extraction method using a resistive-fuse network and an oscillator network [1, 2].

In order to achieve real-time image recognition, VLSI implementation of object extraction is essential. We also propose a pulse modulation circuit for implementing the resistive-fuse/oscillator networks. This circuit utilizes conversion from a pulse modulation signal to a voltage [3] for realizing nonlinear analog dynamics of both networks.

## 2. A new object extraction method for natural scene recognition

The segmentation process only using oscillator networks cannot achieve object extraction because an image is segmented into too small pieces. Although resistive-fuse networks can achieve flexible segmentation depending on an object size, the networks cannot extract each segmented region automatically. Thus, we propose a new method by combining both networks.

Discrete-time dynamics of resistive-fuse networks is expressed as follows:  $O_i(t+1) = O_i(t) - \nu[\sum_{k \in n_i} G(O_i - O_k) + \sigma(O_i - I_i)]$ , where  $I_i$  and  $O_i$  represent an input and output of pixel  $i$ , respectively:  $n_i$  is the neighborhood of  $i$ :  $\nu$  and  $\sigma$  are constant parameters.  $G(\cdot)$  is a voltage-current characteristic of a resistive-fuse, as shown in Fig. 1. By changing the parameter  $\eta$  (See Fig. 1(b)), one can avoid reaching local minima, and segment an image into target objects.

The nonlinear oscillator network model that we have already proposed is shown in Fig. 2. The dynamics of an oscillator is expressed by variables  $x_i$  and  $y_i$ , and includes cubic and hyperbolic-tangent functions of  $x_i$ . This dynamics produces periodic behavior of a single oscillator as shown in Fig. 2(b), and synchronous/asynchronous firing states between oscillators as shown in Fig. 2(c). A region firing synchronously is extracted as an object region.

We confirmed object extraction of a real image by numerical simulation. Original and segmented images are shown in Fig 3(a) and (b), respectively. As shown in Fig 3(b), regions corresponding to recognition objects such as human faces are smoothed, and extracted as shown in Fig. 3(c) and (d), where the image shown in Fig. 3(b) is an input of an oscillator network.

## 3. A pulse modulation circuit for object extraction

A resistive-fuse/oscillator circuit is shown in Fig. 4(a), which is based on the oscillator circuit that we have already proposed [1]. This circuit has two modes: resistive-fuse and oscillator, and the two modes are switched by  $SEL_1$ .

In the resistive-fuse mode, the values of  $O_i$  and  $I_i$  are represented by voltage  $V_{xi}$  and  $V_{yi}$ , and are held at capacitors  $C_{xi}$  and  $C_{yi}$ , respectively. Voltage  $V_{xi}$  is linearly transformed into a pulse width modulation (PWM) signal  $PS_1$  with a pulse width of  $T_i$  by comparator  $COMP_{i1}$ . The absolute difference value  $|O_i - O_k|$  is generated by an XOR gate as a PWM signal  $PS_4$  with a width of  $T_{ik0}$ . Another absolute difference value  $|O_i - I_i|$  is generated by switching signal  $SEL_2$ . The sign of  $O_i - O_k$  is obtained by the sign generator. In our pulse modulation circuit architecture, pulse signals and reference voltage waveforms must be synchronous. Therefore, a pulse  $PS_4$  is linearly transformed into a pulse  $PS_5$  with a width of  $T_{ik}(= T_{ik0})$ . This pulse turns on  $SW_2$  and capacitor  $C_1$  holds the voltage  $V_G(T_{ik})$ , where  $V_G$  varies in the time-domain:  $V_G(t) = G(t)$ . Voltage  $V_G(T_{ik})$  is linearly transformed into a pulse  $PS_6$  with a width of  $G(|O_i - O_k|)$ . By using the sign signal, charges corresponding to the value  $G(O_i - O_k)$  are injected into or extracted from  $C_{xi}$  in each time step. Thus, nonlinear transformation  $G(\cdot)$  can be obtained by using PWM signals and nonlinear reference voltage waveform  $V_G(t)$ .

In the oscillator mode, variables  $x_i$  and  $y_i$  in the dynamics of an oscillator are represented by voltages  $V_{xi}$  and  $V_{yi}$ . The cubic and hyperbolic-tangent functions are generated by converting from voltages into pulse phase modulation (PPM) signals and switching nonlinearly modulated current sources [1]. The PPM signals switch current sources, and small charges corresponding to finite differences of  $x_i$  and  $y_i$  are injected into or extracted from  $C_{xi}$  and  $C_{yi}$  in each time step.

## 4. Circuit simulation results

We performed circuit simulation (HSPICE) of the proposed circuit. The device parameters used were based on a  $0.6\mu\text{m}$  CMOS process, and the supply voltage was 5.0V. As shown in Fig. 4(c) and (d), the expected resistive-fuse characteristic and oscillation were obtained. Thus, it was confirmed that the proposed circuit precisely implements the dynamics of resistive-fuse and oscillator networks.

## 5. Conclusion

We proposed a new object extraction method using resistive-fuse/oscillator networks.

Moreover, we proposed a PWM/PPM circuit for this method. This circuit can implement both functions of resistive-fuse and oscillator networks by using the same circuit components.

## Acknowledgments

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## References

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- [2] H. Ando, et al., in *ICANN99*, 655-660 (1999)
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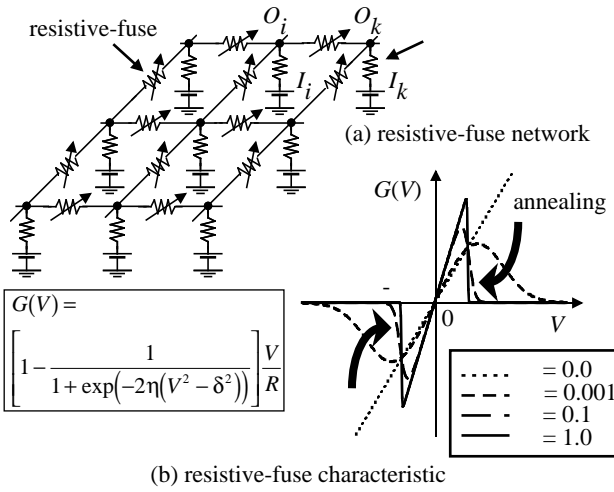


Figure 1: Resistive-fuse model

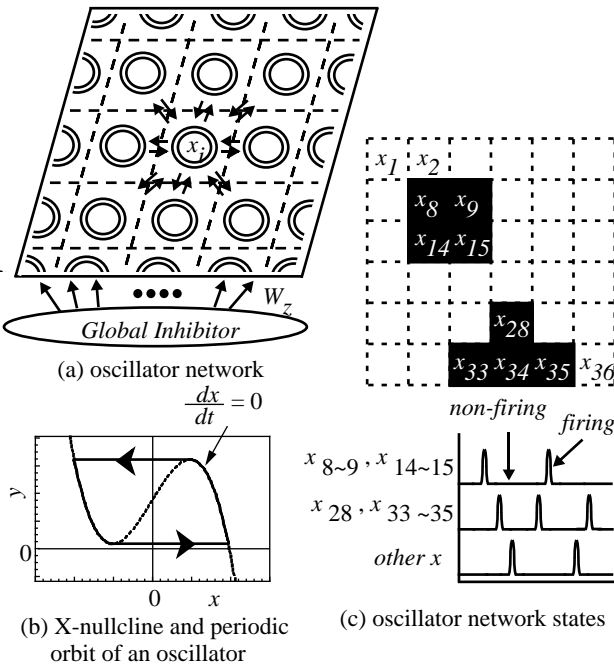


Figure 2: Oscillator network model

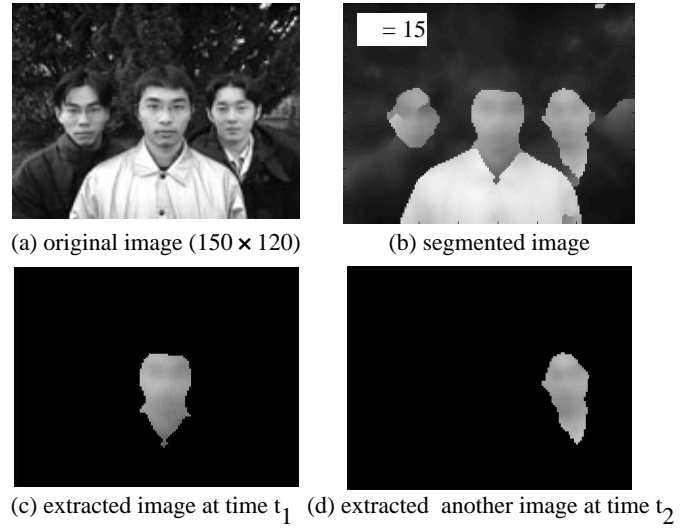


Figure 3: Numerical simulation results

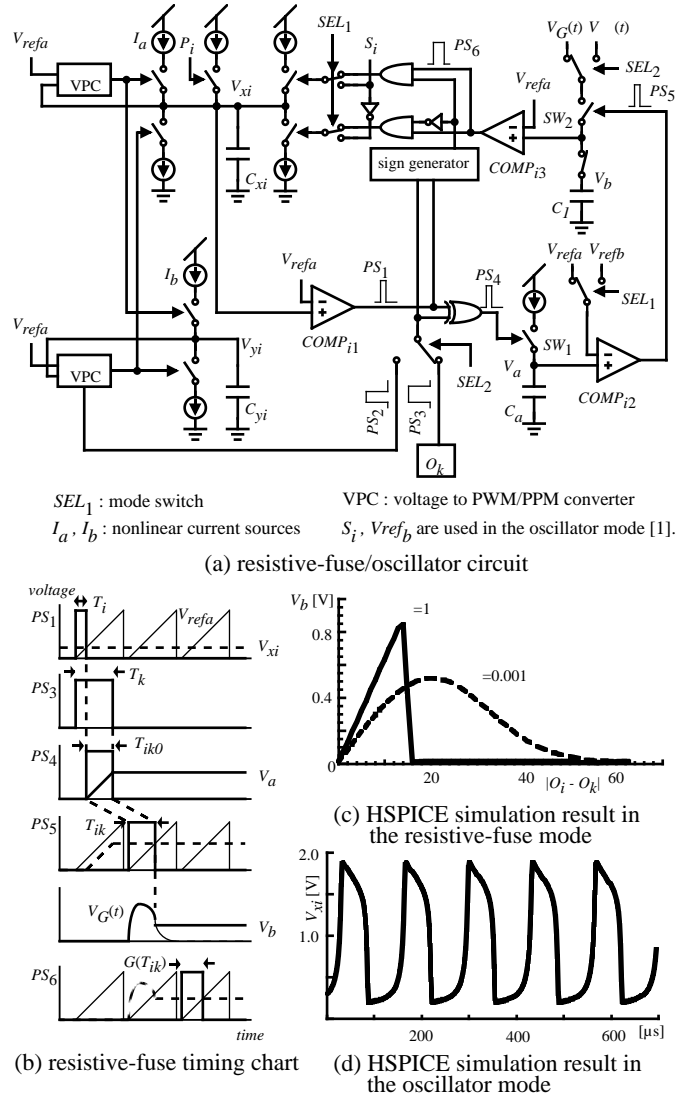


Figure 4: Resistive-fuse/oscillator circuit